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PAPER-2: Paper Analysis

**UPSC CSE MAIN 2024**

**Mathematics Optional**



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UPSC CSM 2024 MATHEMATICS OPTIONAL PAPER-2 ANALYSIS

1. (a) Let  $G$  be a finite group of order  $mn$ , where  $m$  and  $n$  are prime numbers with  $m > n$ . Show that  $G$  has at most one subgroup of order  $m$ .

(b) If  $w = f(z)$  is an analytic function of  $z$ , then show that

$$\left( \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) \log |f'(z)| = 0$$

(c) Test the convergence of  $\int_0^2 \frac{\log x}{\sqrt{(2-x)}} dx$

(d) If  $\phi$  and  $\psi$  are function of  $x$  and  $y$  satisfying Laplace equation, then show that

$$f(z) = p + iq, i = \sqrt{-1} \text{ is an analytic function, where } p = \frac{\partial \phi}{\partial y} - \frac{\partial \psi}{\partial x} \text{ and } q = \frac{\partial \phi}{\partial x} + \frac{\partial \psi}{\partial y}$$

(e) Use two phase method to solve the following linear programming problem:

Maximize  $z = x_1 + 2x_2$

Subject to  $x_1 - x_2 \geq 3$   
 $2x_1 + x_2 \leq 10$   
 $x_1, x_2 \geq 0$



2. (a) Using Cauchy's general principle of convergence, examine the convergence of the sequence  $\langle f_n \rangle$ , where  $f_n = 1 + \frac{1}{1!} + \frac{1}{2!} + \dots + \frac{1}{n!}$ .

(b) Show that every homomorphic image of an abelian group is abelian, but the converse is not necessarily true.

(c) Find the function which is analytic inside and on the circle  $C: z = e^{i\theta}, 0 \leq \theta \leq 2\pi$  and has the value  $\frac{(a^2 - 1)\cos\theta + i(a^2 + 1)\sin\theta}{a^4 - 2a^2 \cos 2\theta + 1}$  on the circumference of  $C$ , where  $a^2 > 1$ .

3. (a) Locate the poles and their order for the function  $f(z) = \frac{1}{z(\sin \pi z)\left(z + \frac{1}{2}\right)}$ . Also, find the residue of  $f(z)$  at these poles.

(b) Consider the series  $\sum_{n=1}^{\infty} U_n(x)$ ,  $0 \leq x \leq 1$ , the sum of whose first  $n$  terms is given by  $S_n(x)$

$$S_n(x) = \frac{1}{2n^2} \log(1 + n^4 x^2), x \in [0, 1].$$

Show that the given series can be differentiated term-by-term, though  $\sum_{n=1}^{\infty} U_n'(x)$ , does not converge uniformly on  $[0, 1]$ .

(c) Using duality principle, solve the following linear programming problem:

$$\text{Minimize } z = 4x_1 + 3x_2 + x_3$$

$$\text{Subject to } x_1 + 2x_2 + 4x_3 \geq 12$$

$$3x_1 + 2x_2 + x_3 \geq 8$$

$$x_1, x_2, x_3 \geq 0$$

4. (a) Consider the polynomial ring  $Z[x]$  over the ring  $Z$  of integers. Let  $S$  be an ideal of  $Z[x]$  generated by  $x$ . Show that  $S$  is prime but not a maximal ideal of  $Z[x]$ .

(b) Find the upper and lower Riemann integrals for the function  $f$  defined on  $[0, 1]$  as follows:

$$f(x) = \begin{cases} (1-x^2)^{1/2}, & \text{if } x \text{ is rational} \\ (1-x), & \text{if } x \text{ is irrational} \end{cases}$$

Hence, show that  $f$  is not Riemann integrable on  $[0, 1]$ .

(c) The personnel manager of a company wants to assign officers A, B and C to the regional offices at Delhi, Mumbai, Kolkata and Chennai. The cost of relocation (in thousand Rupees) of the three officers at the four regional offices are given below:

Officer	Delhi	Mumbai	Kolkata	Chennai
A	16	22	24	20
B	10	32	26	16
C	10	20	46	30

Find the assignment which minimizes the total cost of relocation and also determine the minimum cost.

### SECTION B

5. (a) Show that if  $f$  and  $g$  are arbitrary function of their respective arguments, then

$$u = f(x - kt + iay) + g(x - kt - iay), \text{ is a solution of } \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = \frac{1}{C^2} \frac{\partial^2 u}{\partial t^2}, \text{ where } \alpha^2 = 1 - \frac{k^2}{C^2}$$

(b) Solve the following system of linear equation by Gauss-Jordan method:

$$2x + 3y - z = 5$$

$$4x + 4y - 3z = 3$$

$$2x - 3y + 2z = 2$$

- (c) (i) Determine the decimal equivalent in sign magnitude form of  $(8D)_{16}$  and  $(FF)_{16}$ .
- (ii) Determine the decimal equivalent of  $(9B2.1A)_{16}$ .

(d) A rough uniform board of mass  $m$  and length  $2a$  rests on a smooth horizontal plane and a man of mass  $M$  walks on it from one end to the other. Find the distance covered by the board during this time.

(e) The velocity potential  $\phi$  of a flow is given by

$$\phi = \frac{1}{2}(x^2 + y^2 - 2z^2)$$

Determine the streamlines.

6. (a) Show that the solution of the two-dimensional Laplace's equation

$$\frac{\partial^2 \phi(x, y)}{\partial x^2} + \frac{\partial^2 \phi(x, y)}{\partial y^2} = 0, \quad x \in (-\infty, \infty), y \geq 0$$

Subject to the boundary condition  

$$\phi(x, 0) = f(x), x \in (-\infty, \infty)$$

Along with  $\phi(x, y) \rightarrow 0$  for  $|x| \rightarrow \infty$  and  $y \rightarrow \infty$  can be written in the form

$$\phi(x, y) = \frac{y}{\pi} \int_{-\infty}^{\infty} \frac{f(\xi) d\xi}{y^2 + (x - \xi)^2}$$

(b) Draw the logical circuit for the Boolean expression

$Y = ABC\bar{C} + B\bar{C} + \bar{A}B$ . Also obtain the output  $Y$  (truth table) for the three input bit sequences:

$A = 10001111, B = 00111100, C = 11000100$

(c) Find the moment of inertia of a quadrant of an elliptic disk  $\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$  of mass  $M$  about the line passing through its centre and perpendicular to its plane. Given that the density at any point is proportional to  $xy$ .

7. (a) Find the integral surface of the following quasi-linear equation

$$(y - \phi) \frac{\partial \phi}{\partial x} + (\phi - x) \frac{\partial \phi}{\partial y} = x - y$$

Which passes through the curve  $\phi=0$ ,  $xy = 1$  and through the circle  $x + y + \phi = 0, x^2 + y^2 + \phi^2 = a^2$

(b) Integrate  $f(x) = 5x^3 - 3x^2 + 2x + 1$  from  $x = -2$  to  $x = 4$  using

(i) Simpson's  $\frac{3}{8}$  rule with width  $h = 1$ , and

(ii) Trapezoidal rule with width  $h = 1$ .

(c) Let the velocity field

$$u(x, y) = \frac{B(x^2 - y^2)}{(x^2 + y^2)^2}, \quad v(x, y) = \frac{2Bxy}{(x^2 + y^2)^2}, \quad w(x, y) = 0$$

Satisfy the equation of motion for inviscid incompressible flow, where  $B$  is a constant. Determine the pressure associated with this velocity field.

8. (a) Solve the partial differential equation

$$\frac{\partial}{\partial y} \left( \frac{\partial \phi}{\partial x} + \phi \right) + 2x^2 y \left( \frac{\partial \phi}{\partial x} + \phi \right) = 0$$

By transforming it to the canonical form.

(b) Using Newton's forward difference formula for interpolation, estimate the value of  $f(2.5)$  from the following data:

$x$ :	1	2	3	4	5	6
$f(x)$ :	0	1	8	27	64	123

(c) Suppose an infinite liquid contains two parallel, equal and opposite rectilinear vortices at a distance  $2a$ . Show that the streamlines relative to the vortex and given by the equation

$$\log \frac{x^2 + (y-a)^2}{x^2 + (y+a)^2} + \frac{y}{a} = C$$

Where  $C$  is a constant, the origin is the middle point of the join, and the line joining the vortices is the axis of  $y$ .

## ANALYSIS & ANSWERS

### 1. (a)

We know that; For two finite subgroups H and K of a group,

define the set  $HK = \{hk \mid h \in H, k \in K\}$ . Then,

$$|HK| = |H||K|/|H \cap K|. \text{ i.e. } \boxed{o(HK) = \frac{o(H).o(K)}{o(H \cap K)}} \dots(1)$$

Now let if G has two distinct subgroups H and K of order m; then,

$$\text{By (1); } o(HK) = \frac{o(H).o(K)}{o(H \cap K)} = \frac{m.m}{1} = m^2 ; \dots(2)$$

But  $o(G) = m.n$ , so order of subgroup of G must be less than equal to order of G.

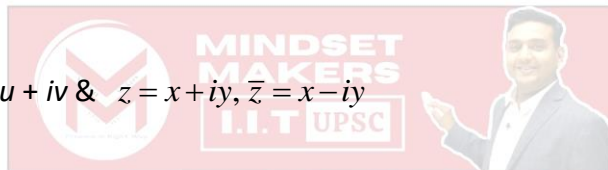
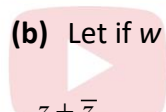
$$\text{So, } o(HK) \leq m.n \dots(3)$$

i.e. (2) is not possible because  $m > n \Rightarrow m^2 > m.n$

### 1. (b) Let if $w = f(z) = u + iv$ & $z = x + iy, \bar{z} = x - iy$

$$\therefore x = \frac{z + \bar{z}}{2}, y = \frac{z - \bar{z}}{2i}$$

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Now using: If  $\phi$  is function of x and y and x,y are functions of  $z$  &  $\bar{z}$ ; then

$$\partial\phi = \frac{\partial\phi}{\partial x} \cdot \partial x + \frac{\partial\phi}{\partial y} \cdot \partial y$$

$$\Rightarrow \frac{\partial\phi}{\partial z} = \frac{\partial\phi}{\partial x} \cdot \frac{\partial x}{\partial z} + \frac{\partial\phi}{\partial y} \cdot \frac{\partial y}{\partial z} \Rightarrow \frac{\partial\phi}{\partial z} = \frac{\partial\phi}{\partial x} \cdot \frac{1}{2} + \frac{\partial\phi}{\partial y} \cdot \frac{1}{2i} \Rightarrow \frac{\partial\phi}{\partial z} = \frac{\partial\phi}{\partial x} \cdot \frac{1}{2} + \frac{\partial\phi}{\partial y} \cdot \frac{1}{2i} \dots(1)$$

$$\text{And, } \frac{\partial\phi}{\partial \bar{z}} = \frac{\partial\phi}{\partial x} \cdot \frac{\partial x}{\partial \bar{z}} + \frac{\partial\phi}{\partial y} \cdot \frac{\partial y}{\partial \bar{z}} \Rightarrow \frac{\partial\phi}{\partial \bar{z}} = \frac{\partial\phi}{\partial x} \cdot \frac{1}{2} - \frac{\partial\phi}{\partial y} \cdot \frac{1}{2i} \Rightarrow \frac{\partial\phi}{\partial \bar{z}} = \frac{\partial\phi}{\partial x} \cdot \frac{1}{2} - \frac{\partial\phi}{\partial y} \cdot \frac{1}{2i} \dots(2)$$

Using (1) and (2), we get

$$\frac{\partial^2}{\partial z \partial \bar{z}} = \left( \frac{\partial}{\partial x} \cdot \frac{1}{2} + \frac{\partial}{\partial y} \cdot \frac{1}{2i} \right) \left( \frac{\partial}{\partial x} \cdot \frac{1}{2} - \frac{\partial}{\partial y} \cdot \frac{1}{2i} \right) = \frac{1}{4} \left( \frac{\partial^2}{\partial x^2} - \frac{\partial^2}{\partial y^2} \right)$$

$$\left(\frac{\partial^2}{\partial x^2} - \frac{\partial^2}{\partial y^2}\right) = 4 \frac{\partial^2}{\partial z \partial \bar{z}}$$

$$\therefore \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2}\right) \log |f'(z)| = 4 \frac{\partial^2}{\partial z \partial \bar{z}} \times \frac{1}{2} \log |f'(z)|^2$$

$$= 2 \frac{\partial^2}{\partial z \partial \bar{z}} \log \{f'(z) \cdot f'(\bar{z})\} \quad \text{logic always works for } \because |\phi(z)|^2 = \phi(z) \phi(\bar{z}) \phi(\bar{z}) \phi(z)$$

$$= 2 \frac{\partial^2}{\partial z \partial \bar{z}} [\log f'(z) + \log f'(\bar{z})]$$

$$= 2 \frac{\partial}{\partial z} \left[ \frac{f''(\bar{z})}{f'(\bar{z})} \right] = 0$$

$$\left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2}\right) \log |f'(z)| = 0$$

1. (c) given,  $I = \int_0^2 \frac{\log x}{\sqrt{2-x}} dx$



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As, the given improper integral is of 2<sup>nd</sup> kind & gives infinity at  $x = 0$  & at  $x = 2$ .

$$\therefore I = \int_0^1 \frac{\log x}{\sqrt{2-x}} dx + \int_1^2 \frac{\log x}{\sqrt{2-x}} dx \dots (1)$$

- checking the convergence of  $\int_0^1 \frac{\log x}{\sqrt{2-x}} dx$

$$\lim_{x \rightarrow 0} (x-0)^\mu \times \frac{\log x}{\sqrt{2-x}} = \lim_{x \rightarrow 0} \frac{x^\mu \log x}{\sqrt{2-x}} = \frac{1}{\sqrt{2}} \lim_{x \rightarrow 0} x^\mu \log x = 0 \text{ for } 0 < \mu < 1$$

As,  $\mu < 1$ , so,  $\int_0^1 \frac{\log x}{\sqrt{2-x}} dx$  is convergent ... (1)

- checking the convergence of  $\int_1^2 \frac{\log x}{\sqrt{2-x}} dx$

Take  $g(x) = \frac{1}{\sqrt{2-x}}$

$$\therefore \lim_{x \rightarrow 2} \frac{f(x)}{g(x)} = \lim_{x \rightarrow 2} \frac{\frac{\log x}{\sqrt{2-x}}}{\frac{1}{\sqrt{2-x}}} = \lim_{x \rightarrow 2} \log x = \log 2, \text{ which is finite \& non-zero}$$

$\therefore$  By comparison test both  $\int_1^2 \frac{\log x}{\sqrt{2-x}} dx$  &  $\int_1^2 \frac{1}{\sqrt{2-x}} dx$  converges or diverges together.

As,  $\int_1^2 \frac{1}{\sqrt{2-x}} dx$  is convergent  $\left[ \because \int_a^b \frac{dx}{(x-a)^n} \text{ is convergent for } n < 1 \right]$

$$\therefore \int_1^2 \frac{\log x}{\sqrt{2-x}} dx \text{ is also convergent....(2)}$$

$\therefore$  From (1) & (2),  $\int_0^2 \frac{\log x}{\sqrt{2-x}} dx$  is convergent.



1. (d) given,  $\phi(x, y)$  &  $\psi(x, y)$  satisfies Laplace equation.

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$$\therefore \frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} = 0 \quad \text{.....(1)}$$

$$\frac{\partial^2 \psi}{\partial x^2} + \frac{\partial^2 \psi}{\partial y^2} = 0 \quad \text{.....(2)}$$

Also, given,

$$p = \frac{\partial \phi}{\partial y} - \frac{\partial \psi}{\partial x} \quad \& \quad \text{.....(3)}$$

$$q = \frac{\partial \phi}{\partial x} + \frac{\partial \psi}{\partial y} \quad \text{.....(4)}$$

Now,

$$\frac{\partial p}{\partial x} = \frac{\partial}{\partial x} \left( \frac{\partial \phi}{\partial y} - \frac{\partial \psi}{\partial x} \right) = \frac{\partial^2 \phi}{\partial x \partial y} - \frac{\partial^2 \psi}{\partial x^2}$$



$$\frac{\partial p}{\partial y} = \frac{\partial}{\partial y} \left( \frac{\partial \phi}{\partial y} - \frac{\partial \psi}{\partial x} \right) = \frac{\partial^2 \phi}{\partial y^2} - \frac{\partial^2 \psi}{\partial y \partial x}$$

$$\frac{\partial q}{\partial x} = \frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \psi}{\partial x \partial y}$$

$$\frac{\partial q}{\partial y} = \frac{\partial^2 \phi}{\partial y \partial x} + \frac{\partial^2 \psi}{\partial y^2}$$

Now,

$$\frac{\partial p}{\partial x} - \frac{\partial q}{\partial y} = - \left( \frac{\partial^2 \psi}{\partial x^2} + \frac{\partial^2 \psi}{\partial y^2} \right)$$

$$\frac{\partial p}{\partial x} - \frac{\partial q}{\partial y} = 0 \{ \text{using (2)} \}$$

$$\boxed{\frac{\partial p}{\partial x} = \frac{\partial q}{\partial y}}$$

$$\frac{\partial p}{\partial y} + \frac{\partial q}{\partial x} = \frac{\partial^2 \phi}{\partial y^2} - \frac{\partial^2 \psi}{\partial y \partial x} + \frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \psi}{\partial x \partial y}$$

$$\frac{\partial p}{\partial y} + \frac{\partial q}{\partial x} = \frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} = 0 \{ \text{using (1)} \}$$

$$\therefore \boxed{\frac{\partial p}{\partial y} = - \frac{\partial q}{\partial x}}$$

Also,  $\frac{\partial p}{\partial x}$ ,  $\frac{\partial p}{\partial y}$ ,  $\frac{\partial q}{\partial x}$  &  $\frac{\partial q}{\partial y}$  are continuous

So,  $f(z) = p + iq$  is an analytic function.

1. (e) Max  $z = x_1 + 2x_2$

sub to,  $x_1 - x_2 \geq 3$

$2x_1 + x_2 \leq 10$

$x_1, x_2 \geq 0$

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Standard form:

$$\text{Max } z = x_1 + 2x_2$$

$$\text{sub to, } x_1 - x_2 - s_1 + a_1 = 3$$

$$2x_1 + x_2 + s_2 = 10$$

$$\text{s.t } x_1, x_2, s_1, s_2, \geq 0$$

Here,  $a_1$  is artificial variable.

**Phase I**

$$\text{max } z^* = 0x_1 + 0x_2 + 0 \cdot s_1 + 0s_2 - 1 \cdot a_1$$

$$\text{sub to, } x_1 - x_2 - s_1 + a_1 = 3$$

$$2x_1 + x_2 + s_2 = 10$$

$$\text{s.t } x_1, x_2, s_1, s_2, a_1 \geq 0$$



$C_j \rightarrow 0 \quad 0 \quad 0 \quad 0 \quad -1$   
 $B, C_B \quad X_B \quad Y_1 \quad Y_2 \quad Y_3 \quad Y_4 \quad Y_5 \quad \text{Min } \frac{X_B}{Y_1}$   
 $a_1, -1 \quad 3 \quad 1 \quad -1 \quad -1 \quad 0 \quad 1 \quad 3 \rightarrow$   
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	$S_2, 0$	10	2	1	0	1	0	5
	$\Delta j \rightarrow$	1	-1	-1	0	0		

		$\uparrow$						
	$C_j \rightarrow$	0	0	0	0	-1		
$B, C_B$	$X_B$	$Y_1$	$Y_2$	$Y_3$	$Y_4$	$Y_5$	$\text{Min } X_B$	
$x_1, 0$	3	1	-1	-1	0	1		
$S_2, 0$	4	0	3	2	1	-2		
	$\Delta j \rightarrow$	0	0	0	0	-1		

$\therefore$  all  $\Delta j's \leq 0$  & No artificial variable, is present in phase I.

So, it works as initial bfs for phase II.

**Phase II**

$$C_j \rightarrow 5 \quad 8 \quad 0 \quad 0$$

B, C <sub>B</sub>	X <sub>B</sub>	Y <sub>1</sub>	Y <sub>2</sub>	Y <sub>3</sub>	Y <sub>4</sub>	Min
x <sub>1</sub> , 5	3	1	-1	-1	0	-ve
S <sub>2</sub> , 0	4	0	3	2	1	$\frac{4}{3} \rightarrow$
$\Delta_j \rightarrow$	0	13	5	0		

B, C <sub>B</sub>	X <sub>B</sub>	Y <sub>1</sub>	Y <sub>2</sub>	Y <sub>3</sub>	Y <sub>4</sub>	Min
C <sub>j</sub> →	5	8	0	0		
x <sub>1</sub> , 5	$\frac{13}{3}$	1	0	$-\frac{1}{3}$	$\frac{1}{3}$	
x <sub>2</sub> , 8	$\frac{4}{3}$	0	1	$\frac{2}{3}$	$\frac{1}{3}$	
$\Delta_j \rightarrow$	0	0	-ve	-ve		

$\therefore$  all  $\Delta_j$ 's  $\leq 0$

$\therefore$  Current bfs is optimal

$\therefore$  Required optimal sol. is  $x_1 = \frac{13}{3}$  &  $x_2 = \frac{4}{3}$

Optimal value =  $\frac{13}{3} + 2 \times \frac{4}{3} = \frac{21}{3} = 7$

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2. (a) Given,  $f_n = 1 + \frac{1}{1!} + \frac{1}{2!} + \dots + \frac{1}{n!}$

• For  $n \geq m$ ,

$$|f_n - f_m| = \left| 1 + \frac{1}{1!} + \dots + \frac{1}{m!} + \frac{1}{(m+1)!} + \dots + \frac{1}{n!} - \left( 1 + \frac{1}{1!} + \dots + \frac{1}{m!} \right) \right|$$

$$= \frac{1}{(m+1)!} + \frac{1}{(m+2)!} + \dots + \frac{1}{n!}$$

$$\leq \frac{1}{2^m} + \frac{1}{2^{m+1}} + \dots + \frac{1}{2^{n-1}}$$

$$\leq \frac{\frac{1}{2^m} \left( 1 - \left( \frac{1}{2} \right)^{n-m} \right)}{1 - \frac{1}{2}}$$

$$\leq \frac{2}{2^m}$$

$$|f_n - f_m| \leq \frac{1}{2^{m-1}}$$

• Now for  $\epsilon > 0, |f_n - f_m| < \epsilon$  if  $\frac{1}{2^{m-1}} < \epsilon$

$$\Rightarrow 2^{m-1} < \frac{1}{\epsilon}$$

$$\Rightarrow (m-1)\log 2 > \log\left(\frac{1}{\epsilon}\right)$$

$$\Rightarrow m-1 > \log\left(\frac{1}{\epsilon}\right) \cdot (\log 2)^{-1}$$

$$\Rightarrow m > 1 + \log\left(\frac{1}{\epsilon}\right) \cdot (\log 2)^{-1} \quad \dots(1)$$

• Therefore, For each  $\epsilon > 0$ , there exists  $m \in \mathbb{N}$  s.t

$$|f_n - f_m| < \epsilon \forall n \geq m$$

So,  $\langle f_n \rangle$  is a convergent sequence by Cauchy's general principle of convergence.

**2. (b) Homomorphic image of abelian group is abelian i.e.**

$f : G \rightarrow G'$  is an onto homomorphism, if  $G$  is abelian then  $G'$  is abelian.

Let  $f : G \rightarrow G'$  is onto homomorphism and  $G$  is abelian then  $xy = yx, \forall x, y \in G$

Let  $f(x) \in G', f(y) \in G'$

$$f(x) \cdot f(y) = f(xy) \quad [ \because f \text{ is homomorphism} ]$$

$$= f(yx) \quad [ xy = yx, \because G \text{ is abelian} ]$$

$$= f(y) \cdot f(x)$$

$$\Rightarrow f(x) \cdot f(y) = f(y) \cdot f(x), \forall f(x), f(y) \in G' \text{ then } G' \text{ is abelian. [Proved]}$$

Converse of the above theorem need not be true

$f : S_3 \rightarrow Z_2$  with  $\ker f = A_3$  then

$$\frac{S_3}{A_3} \approx Z_2$$

i.e.  $f(S_3) \approx Z_2$  with  $\ker f = A_3$

$Z_2$  is abelian but  $S_3$  is non-abelian.

2. (c)  $\because$  Given that  $f(z)$  at  $|z| = 1$  is  $\frac{(a^2 - 1)\cos\theta + 1(a^2 + 1)\sin\theta}{a^4 - 2a^2\cos\theta + 1}$

$$\therefore f = \frac{a^2 \cdot e^{i\theta} - e^{-i\theta}}{(a^2 - e^{i2\theta})(a^2 - e^{-i2\theta})}$$

$\therefore f(z)$  is analytic for  $|z| \leq 1$ .

$\therefore$  By Taylor's theorem, we have

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Now, let's find  $a_n$ ;

$$a_n = \frac{1}{2\pi i} \int_c \frac{a^2 \cdot e^{i\theta} - e^{-i\theta}}{(e^{i\theta})^{n+1}} \cdot \frac{ie^{i\theta} d\theta}{(a^2 - e^{i2\theta})(a^2 - e^{-i2\theta})}$$

$$= \frac{1}{2\pi i} \int_c \frac{e^{-i(n-1)\theta}}{a^2} \left(1 - \frac{e^{i2\theta}}{a^2}\right)^{-1} d\theta$$

$$= \frac{1}{2\pi a^2} \int_{\theta=0}^{2\pi} \frac{e^{-i(n-1)\theta}}{a^2} \left(1 - \frac{e^{i2\theta}}{a^2}\right)^{-1} d\theta \quad \dots(1)$$

$$\because \int_0^{2\pi} e^{i\alpha\theta} d\theta = 0 \text{ for } \alpha \neq 0, \quad \dots(2)$$

$$\therefore a_n = \frac{1}{2\pi a^2} \int_0^{2\pi} e^{-i2m\theta} \cdot \frac{e^{i2m\theta}}{a^{2m}} d\theta; \text{ using (2) in (1), putting for } n \text{ odd, } n-1 = 2m$$



$$= \frac{1}{2\pi a^2} \cdot \frac{2\pi}{a^2 m} = \frac{1}{a^2 a^{n-1}}$$

$$\therefore a_n = \frac{1}{a^{n+1}} \text{ where } n \text{ is odd.}$$

$$\therefore f(z) = \sum_{n=0}^{\infty} a_n z^n = \sum_{n=0}^{\infty} \frac{1}{a^{n+1}} z^n = \frac{1}{a} \sum_{n=1,3,5,7,\dots} \left(\frac{z}{a}\right)^n$$

$$\Rightarrow f(z) = \frac{1}{a} \frac{z}{a \left(1 - \left(\frac{z}{a}\right)^2\right)}$$

$$\Rightarrow f(z) = \frac{z}{a^2 - z^2}$$

$$3. \text{ (a) } f(z) = \frac{1}{z(\sin \pi z) \left(z + \frac{1}{2}\right)}$$

• For poles of  $f(z)$ , let's put denominator as zero.

$$z \sin \pi z \left(z + \frac{1}{2}\right) = 0$$

$z \sin \pi z = 0 \Rightarrow z = 0, \pm 1 \pm 2, \dots$ . It must be noticed here that as the denominator is consisting of

$z \cdot \sin \pi z$ , so  $z = 0$  will become a pole of order 2.  $\lim_{z \rightarrow 0} z^2 f(z) \neq 0$ .

$z = \pm 1 \pm 2, \dots$  are simple poles

or  $z + \frac{1}{2} = 0 \Rightarrow z = -\frac{1}{2}$  is a pole of order 1.

• Now, Residue of  $f(z)$  at  $z = 0$  is:

$$\lim_{z \rightarrow 0} \frac{d}{dz} \left( z^2 f(z) \right) = \lim_{z \rightarrow 0} \frac{d}{dz} \frac{z^2}{z(\sin \pi z) \left(z + \frac{1}{2}\right)} = \lim_{z \rightarrow 0} \frac{d}{dz} \frac{z}{(\sin \pi z) \left(z + \frac{1}{2}\right)}$$


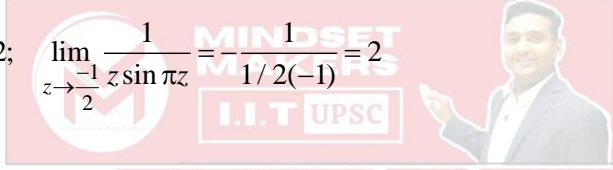

$$\lim_{z \rightarrow 0} \frac{d}{dz} \frac{z}{(\sin \pi z) \left(z + \frac{1}{2}\right)} = \lim_{z \rightarrow 0} \left\{ \frac{\left( (\sin \pi z) \left(z + \frac{1}{2}\right) \cdot 1 - z \left( \sin \pi z \cdot 1 + \pi \cos \pi z \left(z + \frac{1}{2}\right) \right) \right)}{\left( \sin^2 \pi z \right) \left(z + \frac{1}{2}\right)^2} \right\} =$$

$$\lim_{z \rightarrow 0} \left\{ \frac{(\sin \pi z) \left( z + \frac{1}{2} \right)}{(\sin^2 \pi z) \left( z + \frac{1}{2} \right)^2} - \frac{z \sin \pi z}{(\sin^2 \pi z) \left( z + \frac{1}{2} \right)^2} - \frac{\pi z \cos \pi z \left( z + \frac{1}{2} \right)}{(\sin^2 \pi z) \left( z + \frac{1}{2} \right)^2} \right\}$$

$$\lim_{z \rightarrow 0} \left\{ \frac{1}{(\sin \pi z) \left( z + \frac{1}{2} \right)} - \frac{z}{(\sin \pi z) \left( z + \frac{1}{2} \right)^2} - \frac{\pi z \cos \pi z}{(\sin^2 \pi z) \left( z + \frac{1}{2} \right)} \right\} = \lim_{z \rightarrow 0} \left\{ \frac{1}{2(\sin \pi z) \left( z + \frac{1}{2} \right)^2} - \frac{\pi z \cos \pi z}{(\sin^2 \pi z) \left( z + \frac{1}{2} \right)} \right\}$$

$$= \lim_{z \rightarrow 0} \left\{ \frac{(\sin \pi z) \left( z + \frac{1}{2} \right) - \pi z \cos \pi z}{2(\sin^2 \pi z) \left( z + \frac{1}{2} \right)^2} \right\}$$

$$\lim_{z \rightarrow 0} \left\{ \frac{\left\{ \pi z - \frac{\pi^3 z^3}{3!} + \frac{\pi^5 z^5}{5!} - \dots \right\} - \pi z \left\{ 1 - \frac{\pi^2 z^2}{2!} + \frac{\pi^4 z^4}{4!} \right\}}{2 \left\{ \pi z - \frac{\pi^3 z^3}{3!} + \frac{\pi^5 z^5}{5!} - \dots \right\}^2 \left( z + \frac{1}{2} \right)^2} \right\} = \frac{-4}{\pi}$$

- For residue at  $z = -1/2$ ;    $\lim_{z \rightarrow -1/2} \frac{1}{z \sin \pi z} = \frac{1}{1/2(-1)} = 2$
- For residue at  $z = n\pi$ ;  $\lim_{z \rightarrow n\pi} \frac{z - n\pi}{z \sin \pi z (z + 1/2)} = (-1)^n \frac{1}{n\pi(n + \frac{1}{2})}$  

3. (b) Consider the series  $\sum_{n=1}^{\infty} U_n(x), 0 \leq x \leq 1$ ,  $S_n(x) = \frac{1}{2n^2} \log(1 + n^4 x^2), x \in [0, 1]$ .

• For uniform convergence:

$$S'_n(x) = \frac{1}{2n^2} \cdot \frac{1}{(1 + n^4 x^2)} \cdot 2xn^4 = \frac{n^2 x}{(1 + n^4 x^2)}$$

$$\text{Max. } S'_n(x); \text{ at } x = \frac{1}{n^2}. \text{ Also, } \lim_{n \rightarrow \infty} S'_n(x) = 0$$

$$M_n = \text{Sup} |S'_n(x) - 0| = \frac{n^2 \cdot \frac{1}{n^2}}{1 + \frac{1}{n^4}} = \frac{1}{2}. \quad \lim_{n \rightarrow \infty} M_n = 1/2 \neq 0.$$

By  $M_n$ -Test;  $\sum_{n=1}^{\infty} U'_n(x)$  does not converge uniformly in  $[0,1]$ .

• To show that the given series can be differentiated term-by-term, though  $\sum_{n=1}^{\infty} U'_n(x)$ , does not converge uniformly on  $[0, 1]$ :

$$\therefore S'_n(x) = \frac{1}{2n^2} \cdot \frac{1}{(1+n^4x^2)} \cdot 2xn^4 = \frac{n^2x}{(1+n^4x^2)} \text{ and Sum function } S'(x) = 0$$

$\therefore \frac{d}{dx} \left\{ \lim_{n \rightarrow \infty} S'_n(x) \right\} = \frac{d}{dx} \left\{ \lim_{n \rightarrow \infty} S(x) \right\} = 0$  shows that yes term by term differentiation is possible.

3. (c) Dual is.

$$\max Z_D = 12w_1 + 8w_2$$

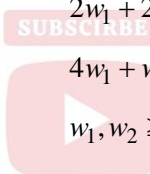
Sub to,

$$w_1 + 3w_2 \leq 4 \quad \dots(1)$$

$$2w_1 + 2w_2 \leq 3 \quad \dots(2)$$

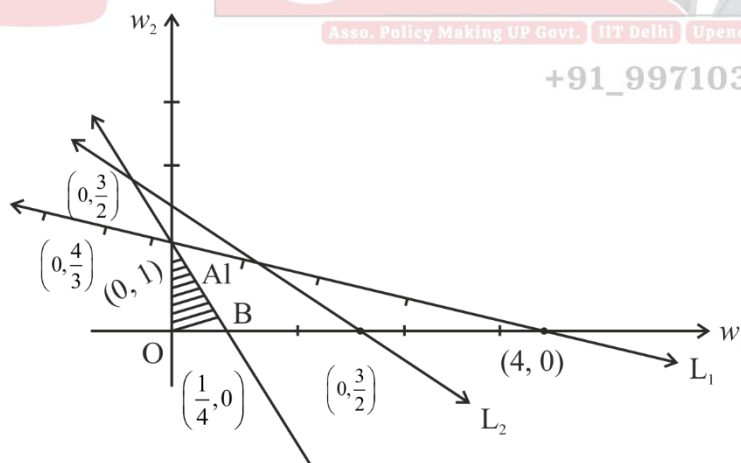
$$4w_1 + w_2 \leq 1 \quad \dots(3)$$

$$w_1, w_2 \geq 0$$



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So, here, the optimal region is OAB,

$$\therefore (Z_D)_O = 0, \quad (Z_D)_A = 8 \quad (Z_D)_B = 12 \times \frac{1}{4} = 3$$

$$\therefore \max Z_D = 8 \text{ at } A(0, 1)$$

$$\therefore \min z = 8$$



4. (a)

Let  $Z[x]$  be the ring of polynomials over the ring of integers  $Z$ .

Let  $S$  be the principal ideal of  $Z[x]$  generated by  $x$  i.e., let  $S = (x)$ .

- We shall show that  $(x)$  is prime but not maximal.

We have  $S = (x) = \{x f(x) : f(x) \in Z[x]\}$ .

First we shall prove that  $S$  is prime.

Let  $a(x), b(x) \in Z[x]$  be such that  $a(x)b(x) \in S$ . Then there exists a polynomial  $c(x) \in Z[x]$  such that

$$xc(x) = a(x)b(x) \quad \dots(1)$$

$$\text{Let } a(x) = a_0 + a_1x + a_2x^2 + \dots, b(x) = b_0 + b_1x + b_2x^2 + \dots$$

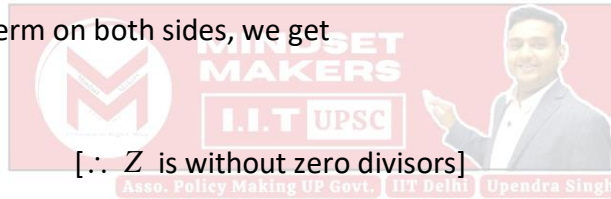
$$c(x) = (c_0 + c_1x + \dots) = (a_0 + a_1x + \dots)(b_0 + b_1x + \dots) \text{ Then (1) becomes}$$

$$x(c_0 + c_1x + \dots) = (a_0 + a_1x + \dots)(b_0 + b_1x + \dots)$$

Equating the constant term on both sides, we get

$$a_0b_0 = 0$$

$$\Rightarrow a_0 = 0 \text{ or } b_0 = 0$$



[ $\therefore Z$  is without zero divisors]

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$$\text{Now } a_0 = 0 \Rightarrow a(x) = a_1x + a_2x^2 + \dots$$

$$\Rightarrow a(x) = (x)(a_1 + a_2x + \dots) \Rightarrow a(x) \in (x)$$

$$\text{Similarly } b_0 = 0 \Rightarrow b(x) = b_1x + b_2x^2 + \dots$$

$$\Rightarrow b(x) = (x)(b_1 + b_2x + \dots) \Rightarrow b(x) \in (x)$$

Thus  $a(x)b(x) \in (x) \Rightarrow$  either  $a(x) \in (x)$  or  $b(x) \in (x)$

Hence  $(x)$  is a prime ideal.

Now we shall show that  $(x)$  is not a maximal ideal of  $Z[x]$ .

For this we must show an ideal  $N$  of  $Z[x]$  such that  $(x)$  is properly contained in  $N$ , while  $N$  itself is properly contained in  $Z[x]$ .

The ideal  $N = (x, 2)$  serves this purpose.

Obviously  $(x) \subseteq (x, 2)$ .

In order to show that  $(x)$  is properly contained in  $(x, 2)$  we must show an element of  $(x, 2)$  which is not in  $(x)$ .

Clearly  $2 \in (x, 2)$ . We shall show that  $2 \notin (x)$ .

Let  $2 \in (x)$ . Then we can write,

$$2 = xf(x) \text{ for some } f(x) \text{ in } Z[x].$$

$$\text{Let } f(x) = a_0 + a_1x + \dots$$

$$\text{Then } 2 = xf(x) \Rightarrow 2 = x(a_0 + a_1x + \dots)$$

$$\Rightarrow 2 = a_0x + a_1x^2 + \dots$$

$$\Rightarrow 2 = 0 + a_0x + a_1x^2 + \dots$$

$$\Rightarrow 2 = 0 \quad [\text{by equality of two polynomials}]$$

But  $2 \neq 0$  in the ring of integers. Hence  $2 \notin (x)$ . Thus  $(x)$  is properly contained in  $(x, 2)$ .

Now obviously  $(x, 2) \subseteq Z[x]$ .

In order to show that  $(x, 2)$  is properly contained in  $Z[x]$ , we must show an element of  $Z[x]$ , which is not in  $(x, 2)$ .

Clearly  $1 \in Z[x]$ .

We shall show that  $1 \notin (x, 2)$ . Let  $1 \in I[x]$  Then we have a relation of the form  $1 = xf(x) + 2g(x)$  where  $f(x), g(x) \in Z[x]$ .

$$\text{Let } f(x) = a_0 + a_1x + \dots, g(x) = b_0 + B_1x + \dots$$

$$\text{Then } 1 = xf(a_0 + a_1x + \dots) + 2(b_0 + B_1x + \dots)$$

$$\Rightarrow 1 = 2b_0 \quad [\text{Equating constant term on both sides}]$$

But there is no integer  $b_0$  such that  $1 = 2b_0$

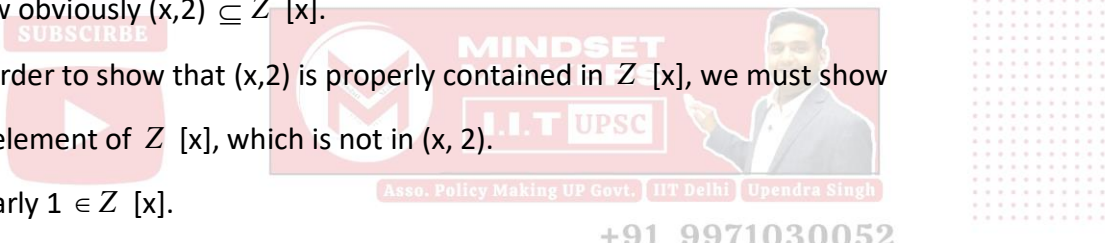
Hence  $1 \notin (x, 2)$  Thus  $(x, 2)$  is properly contained in  $Z[x]$ .

Therefore  $(x)$  is not a maximal ideal of  $Z[x]$ .

#### 4. (c)

**Upper sum**  $(U(P, f))$  is defined as

$$f(x_1)\Delta x_1 + f(x_2)\Delta x_2 + \dots + f(x_n)\Delta x_n$$



; Where  $f(x_i)$  is the maximum value of function in particular i-th subinterval

**Lower sum** ( $L(P, f)$ ) is defined as

$$f(x_1)\Delta x_1 + f(x_2)\Delta x_2 + \dots + f(x_n)\Delta x_n$$

;Where  $f(x_i)$  is the minimum value of function in particular i-th subinterval

Let's take a partition of  $[0,1]$  by dividing into  $n$  sub intervals

$$\text{i.e., } \Delta x = \frac{1-0}{n} = \frac{1}{n}$$

$$x_0 = 0, x_1 = 0 + \frac{1}{n}, x_2 = 0 + \frac{1}{n} + \frac{1}{n} = \frac{2}{n}$$

Partition P is :

$$\begin{array}{cccc} [x_0, x_1] \cup [x_1, x_2] \cup [x_2, x_3] \cup \dots \cup [x_{n-1}, x_n] \\ \downarrow \quad \downarrow \quad \downarrow \quad \downarrow \\ \text{length of} & \Delta x_2 = \frac{1}{n} & \Delta x_3 = \frac{1}{n} & \Delta x_n = \frac{1}{n} \\ \text{subinterval} & & & \end{array}$$

-   $\Delta x_i = \frac{1}{n}$
- $f(x) = \begin{cases} \sqrt{1-x^2}; & x \in \mathbf{Q} \\ 1-x & ; x \in \mathbf{Q}^c \end{cases}$



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For max value of function in i-th interval,  $M_i = 1 - x = 1 - \frac{i}{n}$

$$U(p.f) = \sum_{i=1}^n M_i \Delta x_i = \sum_{i=1}^n \left(1 - \frac{i}{n}\right) \cdot \frac{1}{n} = \frac{1}{n} \left(1 - \left(\frac{1}{n} + \frac{2}{n} + \dots + \frac{n-1}{n} + \frac{n}{n}\right)\right) = \frac{1}{n} \cdot \frac{1}{n} (1 + 2 + 3 + \dots + (n-1)) = \frac{1}{2} \left(1 - \frac{1}{n}\right)$$

$$\text{So, } U(P, f) = \lim_{n \rightarrow \infty} \frac{1}{2} \left(1 - \frac{1}{n}\right) = \frac{1}{2}.$$

For min value of function in i-th interval,  $m_i = \sqrt{1-x^2} = \sqrt{1 - \left(\frac{i}{n}\right)^2}$

$$L(p.f) = \sum_{i=1}^n \sqrt{1 - \left(\frac{i}{n}\right)^2} \cdot \frac{1}{n} = \frac{1}{n} \left( \sqrt{1 - \left(\frac{1}{n^2} + \frac{2^2}{n^2} + \dots + \frac{(n-1)^2}{n^2} + \frac{n^2}{n^2}\right)} \right); \text{ So, } L(P, f) = \pi/4 \text{ for } n \rightarrow \infty.$$

$\therefore U(P, f) \neq L(P, f)$ ; So, given function is not Riemann Integrable.

4. (c) As. The given assignment produce is not balanced so, adding a dummy row, we get the problem as.

	Delhi	Mumbai	Kolkata	Chanai
A	16	22	24	20
B	10	32	26	16
C	10	20	46	30
D	0	0	0	0

A	0	6	8	4	✓ (4)
B	⊗	22	16	6	✓ (1)
C	⊗	10	36	20	✓ (2)
D	⊗	0	⊗	⊗	

✓  
(3)

A	⊗	2	4	0	
B	0	18	12	2	✓ (3)
C	⊗	6	32	16	✓ (1)
D	4	0	⊗	⊗	

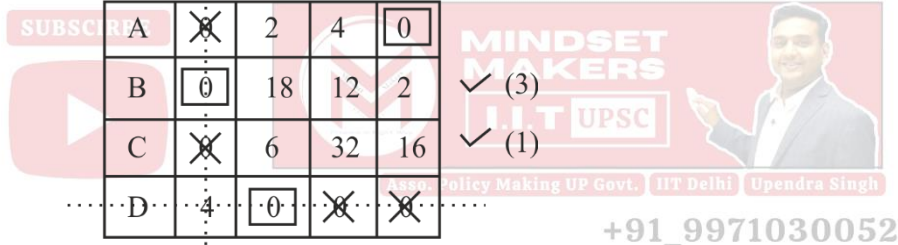
✓  
(2)

A	2	2	4	0	✓ (4)
B	0	16	10	⊗	✓ (3)
C	⊗	4	30	14	✓ (1)
D	6	0	⊗	⊗	

✓  
(2)

✓  
(5)

	Delhi	Mumbai	Kolkata	Chanai
A	2	0	2	⊗
B	⊗	14	8	0
C	0	2	28	14



So, the optimal assignment is

A → Mumbai

B → Chaenai

C → Delhi

D → Kolkata

The minimum cost = 22 + 16 + 10 + 0 = 48

5. (a) Given,  $u = f(x - kt + i\alpha y) + g(x - kt - i\alpha y)$

$$\therefore \frac{\partial u}{\partial x} = f'(x - kt + i\alpha y) + g'(x - kt - i\alpha y)$$

$$\frac{\partial^2 u}{\partial x^2} = f''(x - kt + i\alpha y) + g''(x - kt - i\alpha y)$$

$$\text{And } \frac{\partial u}{\partial y} = f'(x - kt + i\alpha y) \times i\alpha - g'(x - kt - i\alpha y) \times i\alpha$$

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$$\frac{\partial^2 u}{\partial y^2} = f''(x - kt + i\alpha y) \times i^2 \alpha^2 + g''(x - kt - i\alpha y) \times i^2 \alpha^2$$

$$\frac{\partial^2 u}{\partial y^2} = -\alpha^2 [f''(x - kt + i\alpha y) + g''(x - kt - i\alpha y)]$$

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Now,

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = \{f''(x - kt + i\alpha y) + g''(x - kt - i\alpha y)\} (1 - \alpha^2) \quad \dots(1)$$

$$\text{And, } \frac{\partial u}{\partial t} = -k [f'(x - kt + i\alpha y) + g'(x - kt - i\alpha y)]$$

$$\frac{\partial^2 u}{\partial t^2} = k^2 [f''(x - kt + i\alpha y) + g''(x - kt - i\alpha y)] \quad \dots(2)$$

∴ Using (2) in (1)

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = (1 - \alpha^2) \times \frac{1}{k^2} \frac{\partial^2 u}{\partial t^2}$$

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = \frac{1}{k^2} \left\{ 1 - \left( 1 - \frac{k^2}{C^2} \right) \right\} \frac{\partial^2 u}{\partial t^2} \quad [\because \text{Given } \alpha^2 = 1 - \frac{k^2}{C^2}]$$

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = \frac{1}{C^2} \frac{\partial^2 v}{\partial t^2}$$

5. (b) The given system of linear equation in motion notation form is written as  $AX = B$ , where

$$A = \begin{bmatrix} 2 & 3 & -1 \\ 4 & 4 & -3 \\ 2 & -3 & 2 \end{bmatrix}, \quad X = \begin{bmatrix} x \\ y \\ z \end{bmatrix}, \quad B = \begin{bmatrix} 5 \\ 3 \\ 2 \end{bmatrix}$$

$$[A : B] = \left[ \begin{array}{ccc|c} 2 & 3 & -1 & 5 \\ 4 & 4 & -3 & 3 \\ 2 & -3 & 2 & 2 \end{array} \right]$$

$$R_1 \leftrightarrow R_2$$

$$[A : B] = \left[ \begin{array}{ccc|c} 4 & 4 & -3 & 3 \\ 2 & 3 & -1 & 5 \\ 2 & -3 & 2 & 2 \end{array} \right]$$

$$R_1 \rightarrow \frac{1}{4}R_1$$

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$[A : B] = \left[ \begin{array}{ccc|c} 1 & 1 & \frac{-3}{4} & \frac{3}{4} \\ 2 & 3 & -1 & 5 \\ 2 & -3 & 2 & 2 \end{array} \right]$



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$$R_2 \rightarrow R_2 - 2R_1, R_3 \rightarrow R_3 - 2R_1$$

$$[A : B] = \left[ \begin{array}{ccc|c} 1 & 1 & \frac{-3}{4} & \frac{3}{4} \\ 0 & 1 & \frac{1}{2} & \frac{7}{2} \\ 0 & -5 & \frac{7}{2} & \frac{1}{2} \end{array} \right]$$

$$R_3 \rightarrow R_3 + 5R_2, R_1 \rightarrow R_1 - R_2$$

$$[A : B] = \left[ \begin{array}{ccc|c} 1 & 0 & \frac{-5}{4} & \frac{-11}{4} \\ 0 & 1 & \frac{1}{2} & \frac{7}{2} \\ 0 & 0 & 6 & 8 \end{array} \right]$$

$$[A : B] \left[ \begin{array}{ccc|c} 1 & 0 & \frac{-5}{4} & \frac{-11}{4} \\ 0 & 1 & \frac{1}{2} & \frac{7}{2} \\ 0 & 0 & 1 & 3 \end{array} \right]$$

$$R_2 \rightarrow R_2 - \frac{1}{2}R_3, \quad R_1 \rightarrow R_1 + \frac{5}{4}R_3$$

$$[A : B] \left[ \begin{array}{ccc|c} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 2 \\ 0 & 0 & 1 & 3 \end{array} \right]$$

$\therefore$  From  $AX = B$ , we get

$$x = 1$$

$$y = 2$$

$$z = 3$$

### 5. (c)

(i) As we know that in sign magnitude form, the first bit of binary representation represents the sign. If it is 1 then negative sign and 0 then positive sign. Rest of the bits represent the magnitude of that number. So,

$$(8D)_{16} = (10001101)_2 = (-13)_{10} \quad [\because D = 13 \text{ in decimal}]$$

$$1 \underbrace{0001101}_{\text{magnitude}} = (-13)_{10}$$

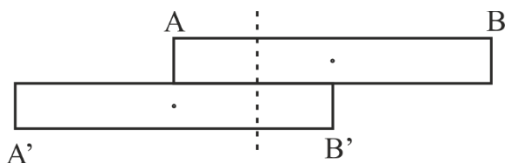
$$(FF)_{16} = (11111111)_2 = 1 \underbrace{1111111}_{\text{magnitude}} = (-127)_{10}$$

$$\begin{aligned} \text{(ii) } (9B2.1A)_{16} &= 9 \times 16^2 + B \times 16 + 2 \times 16^0 + 1 \times \frac{1}{16} + A \times \frac{1}{16^2} \\ &= 9 \times 256 + 11 \times 16 + 2 + 0.0625 + 10 \times 0.00390625 \\ &= 2304 + 176 + 2 + 0.1015625 \\ &= (2482.1015625)_{10} \end{aligned}$$

5. (d) Here, there is internal forces in horizontal direction only the weight of board & man are acting downward & the reaction of the horizontal plane acting upward.

So, By D'Alembert's Principle the C.G. of the system does not move, as the man moves from A to B.

In the initial position,



$$\text{Distance of CG from A} = \frac{M \times 0 + m \times AC}{M + m} = \frac{ma}{M + m}$$

In final position, when the man reaches the point B,

$$\text{Distance of CC from A} = \frac{M \times AB' + mAC'}{M + m}$$

$$= \frac{M(2a - x) + m(a - x)}{M + m}$$

Now, as the position of C of the system remains unchanged

$$\therefore \frac{ma}{M + m} = \frac{M(2a - x) + m(a - x)}{M + m}$$

$$\Rightarrow ma = 2Ma - Mx + ma - ma$$

$$\Rightarrow x(M + m) = 2Ma$$

$$\Rightarrow x = \frac{2Ma}{M + m}$$

5. (e) Given  $\phi = \frac{1}{2}(x^2 + y^2 - 2z^2)$

We know the velocity 'q' can be written as,

$$q = -\nabla\phi$$

$$\Rightarrow u\hat{i} + v\hat{j} + w\hat{k} = -\left(\hat{i}\frac{\partial}{\partial x} + \hat{j}\frac{\partial}{\partial y} + \hat{k}\frac{\partial}{\partial z}\right) \left\{\frac{1}{2}(x^2 + y^2 - 2z^2)\right\}$$

$$\Rightarrow u\hat{i} + v\hat{j} + w\hat{k} = -[x\hat{i} + y\hat{j} - 2z\hat{k}]$$

On comparing we get,

$$u = -x, \quad v = -y, \quad w = 2z$$

$\therefore$  The striations are given by,

$$\frac{dx}{u} = \frac{dy}{v} = \frac{dz}{w}$$

$$\frac{dx}{-x} = \frac{dy}{-y} = \frac{dz}{2z} \quad \dots(1)$$

Taking 1<sup>st</sup> two fraction, of (1)

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$$\frac{dx}{x} = \frac{dy}{y}$$

On integrating,

$\log x = \log y + \log c$ , where  $C_1$  is arbitrary constant

$$x = c_1 y \quad \dots(A)$$

Taking last two fraction, of (1)

$$\frac{dy}{-y} = \frac{dz}{2z}$$

$$\frac{dy}{y} + \frac{dz}{2z} = 0$$

On integrating

$\log y + \frac{1}{2} \log z = \log c_2$ , where  $c_2$  is arbitrary constant

$$y\sqrt{z} = c_2 \quad \dots(B)$$

Equations (A) & (B) gives the equation of streamlines or streamlines are given by

$$\phi\left(\frac{x}{y}, y\sqrt{z}\right) = 0$$

6. (b)  $y = ABC\bar{C} + B\bar{C} + \bar{A}B$

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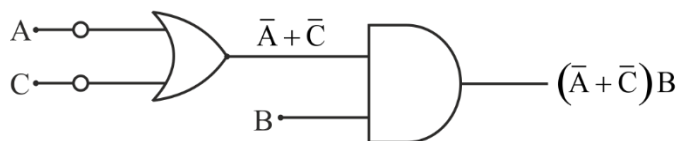
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Step (I): Simplifying the Boolean expression

$$y = ABC\bar{C} + B\bar{C} + \bar{A}B$$

$$= (A+1)B\bar{C} + \bar{A}B$$

Step (II):  $y = B(\bar{C} + \bar{A}) \quad \dots(1)$



Part (II):  $\therefore$  Given

$$A = 1001111, B = 00111100, C = 11000100$$

$$\therefore y = B(\bar{C} + \bar{A}) = (00111100)(01110000 + 00111011)$$

$$= (00111100) (1001001010000011)$$

$$= 0100100000011100011101$$

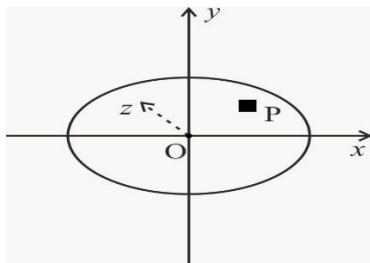
Truth Table for the given input is.

A	B	C	$AB\bar{C}$	$B\bar{C}$	$\bar{A}B$	$y = AB\bar{C} + B\bar{C} + \bar{A}B$
1	0	1	0	0	0	0
0	0	1	0	0	0	0
0	1	0	0	1	1	1
0	1	0	0	1	1	1
1	1	0	1	1	0	1
1	1	1	0	0	0	0



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6. (c)



Let  $P(x, y)$  be the small element with mass  $dm$ .

O; the centre of the elliptic disk

Let the z-axis be the line passing through the centre of elliptic disk and perpendicular to plane of it

$\therefore$  Moment of inertia about OZ, of small element  $dm$  at P.

$$dI = (x^2 + y^2) dm$$

$$\therefore \text{Total moment of inertia of disk about } OZ = \int dI = I$$

$$\therefore I = \iint dm(x^2 + y^2)$$

$$= \iint \rho dx dy (x^2 + y^2) \quad \dots(1)$$

$\therefore$  For rectangular element  $dm = \rho dx dy$

For limits of integration for  $x$  &  $y$  in (1)

$$\text{We have } \frac{x^2}{a^2} + \frac{y^2}{b^2} \leq 1$$

$$I = \iint \alpha xy (x^2 + y^2)$$

**SUBSCRIBE**  $\alpha$  is proportional constant as  $\rho$  is given proportional to  $xy$ .

$$I = \alpha \int_{r=0}^1 \int_{\theta=0}^{\pi/2} r^2 ab \sin \theta \cos \theta \cdot (a^2 \cos^2 \theta + b^2 \sin^2 \theta) r^2 ab r d\theta dr$$

$$I = \alpha a^2 b^2 \int_{r=0}^1 r^5 dr \left( \frac{a^2}{4} + \frac{b^2}{4} \right) = \frac{a}{6} a^2 b^2 \frac{(a^2 + b^2)}{4}$$

$$I = \frac{\alpha}{24} a^2 b^2 (a^2 + b^2) \quad \dots(2)$$

$$\therefore \text{Total mass } M = \iint \rho dx dy = \iint \rho dx dy$$

$$\therefore M = a \int_{r=0}^1 \int_{\theta=0}^{\pi/2} a^2 b^2 r^2 \sin \theta \cos \theta r d\theta dr = \frac{\alpha}{8} a^2 b^2$$

$$\Rightarrow \alpha = \frac{8M}{a^2 b^2} \quad \dots(3)$$

So, on using (3) in (2), we get required moment of inertia =

$$\frac{8M}{a^2 b^2} \cdot \frac{a^2 b^2}{24} (a^2 + b^2) = \frac{1}{3} M (a^2 + b^2)$$

7. (a) On comparing given differential equation with  $Pp + Q.q = R$

We get  $P = y - \phi$ ,  $Q = \phi - x$ ,  $R = x - y$

$\therefore$  Lagrange's auxiliary equations are

$$\frac{dx}{y-\phi} = \frac{dy}{\phi-x} = \frac{d\phi}{x-y} \quad \dots(1)$$

By taking first two fractions of (1), adding then taking with the third fraction, we get,

$$\frac{dx+dy}{y-x} = \frac{d\phi}{x-y} \Rightarrow x+y+\phi = C_1$$

$$\therefore u(x, y, \phi) = x + y + \phi \quad \dots(2)$$

Choosing  $x, y, \phi$  multipliers and then taking the third fraction with it in (1), we get

$$\frac{xdx + ydy + \phi d\phi}{\phi(x-y)} = \frac{d\phi}{x-y} \Rightarrow x^2 + y^2 + \phi^2 = C_2$$

$$\therefore v(x, y, \phi) = x^2 + y^2 + \phi \quad \dots(3)$$

Now using the given conditions in (2) and (3), we get

$$c_1 = 0, c_2 = a^2$$

Parameterizing  $\phi = 0$ ,  $xy = 1$  we get

$$x = t, y = \frac{1}{t}, \phi = 0 \text{ and using in given condition, and then eliminating } t, \text{ we get } c_1^2 - 2 = c_2 \dots(4)$$

$$\therefore \text{ Required integral surface is } (x + y + \phi)^2 - 2 = x^2 + y^2 + \phi^2$$

7. (b) Given  $f(x) = 5x^3 - 3x^2 + 2x + 1$

Given  $a = -2$  &  $b = 4$ . &  $h = 1$

$$x \quad f(x) = y$$

$$x_0 = -2 \quad y_0 = -55$$

$$\begin{array}{ll} x_1 = a + h = -1 & y_1 = -9 \\ x_2 = 0 & y_2 = 1 \\ x_3 = 1 & y_3 = 5 \\ x_4 = 2 & y_4 = 33 \\ x_5 = 3 & y_5 = 115 \\ x_6 = 4 & y_6 = 281 \end{array}$$

Now, By Simpson's  $\frac{3^{\text{th}}}{8}$  rule,

$$\begin{aligned} I &= \int_{-2}^4 f(x) dx = \frac{3h}{8} [(y_0 + y_6) + 3(y_1 + y_2 + y_4 + y_5) + 2 \times y_3] \\ &= \frac{3}{8} [(-55 + 281) + 3(-9 + 1 + 33 + 115) + 2 \times 5] \end{aligned}$$

$$= \frac{3}{8} \times [226 + 420 + 10]$$

$$I = 246$$

(ii) For trapezoidal rule,

Given  $h = 1$

So, the values of  $x_0, x_1, \dots, x_6$  &  $y_0, y_1, \dots, y_6$  will be same.

The formula for trapezoidal rule is given by,

$$\begin{aligned} I &= \int_{-2}^4 f(x) dx = \frac{h}{2} [(y_0 + y_6) + 2(y_1 + y_2 + y_3 + y_4 + y_5)] \\ &= \frac{1}{2} [(-55 + 281) + 2(-9 + 1 + 5 + 33 + 115)] \\ &= \frac{1}{2} [226 + 290] \\ &= 258 \end{aligned}$$

7. (c) Given the velocity field

$$u(x, y) = \frac{B(x^2 - y^2)}{(x^2 + y^2)^2}, v(x, y) = \frac{2Bxy}{(x^2 + y^2)^2}, w(x, y) = 0$$

Satisfies the equation of motion for inside incompressible flow



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The equation of motion are,

$$u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} = \frac{-1}{\rho} \frac{\partial p}{\partial x} \quad \dots(1)$$

$$u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial v}{\partial z} = \frac{-1}{\rho} \frac{\partial p}{\partial y} \quad \dots(2)$$

$$u \frac{\partial w}{\partial x} + v \frac{\partial w}{\partial y} + w \frac{\partial w}{\partial z} = \frac{-1}{\rho} \frac{\partial p}{\partial z} \quad \dots(3)$$

Now,

$$\frac{\partial u}{\partial x} = \frac{(x^2 + y^2)^2 \times 2Bx - B(x^2 - y^2)2(x^2 + y^2) \times 2x}{(x^2 + y^2)^4} = \frac{2Bx(3y^2 - x^2)}{(x^2 + y^2)^3}$$

$$\frac{\partial u}{\partial y} = \frac{(x^2 + y^2) \times (-2By) - B(x^2 - y^2) \times 2(x^2 + y^2) \times 2y}{(x^2 + y^2)^4} = \frac{-2By(3x^2 - y^2)}{(x^2 + y^2)^3}$$

$$\frac{\partial u}{\partial z} = 0$$

$$\frac{\partial v}{\partial x} = \frac{(x^2 + y^2)^2 \times 2By - 2Bxy \times 2(x^2 + y^2) \times 2x}{(x^2 + y^2)^4} = \frac{2By(y^2 - 3x^2)}{(x^2 + y^2)^3}$$

$$\frac{\partial v}{\partial y} = \frac{(x^2 + y^2) \times 2Bx - 2Bxy \times 2(x^2 + y^2) \times 2y}{(x^2 + y^2)^4} = \frac{2Bx(x^2 - 3y^2)}{(x^2 + y^2)^3}$$

$$\frac{\partial v}{\partial z} = 0$$

$$\frac{\partial w}{\partial x} = 0, \frac{\partial w}{\partial y} = 0 \text{ \& } \frac{\partial w}{\partial z} = 0$$

$\therefore$  From (1),

$$\frac{B(x^2 - y^2)}{(x^2 + y^2)^2} \times \frac{2Bx(3y^2 - 3x^2)}{(x^2 + y^2)^3} - \frac{2Bxy}{(x^2 + y^2)^2} \times \frac{2By(3x^2 - y^2)}{(x^2 + y^2)^3} = \frac{-1}{\rho} \frac{\partial p}{\partial x}$$

$$\frac{2B^2x}{(x^2 + y^2)^5} \left[ (x^2 - y^2)(3y^2) - 2y^2(3x^2 - y^2) \right] = \frac{-1}{\rho} \frac{\partial p}{\partial x}$$

$$\frac{2B^2x}{(x^2 + y^2)^5}(-x^4 - 2x^2y^2 - y^4) = \frac{-1}{\rho} \frac{\partial p}{\partial x}$$

$$\frac{-2B^2x}{(x^2 + y^2)^5} \times (x^2 + y^2) = \frac{-1}{\rho} \frac{\partial p}{\partial x}$$

$$\frac{\partial p}{\partial x} = \frac{2B^2x\rho}{(x^2 + y^2)^3}$$

From (2),

$$\frac{B(x^2 - y^2)}{(x^2 + y^2)^2} \cdot \frac{2By(y^2 - 3x^2)}{(x^2 + y^2)^3} + \frac{2Bxy}{(x^2 + y^2)^2} \cdot \frac{2Bx(x^2 - 3y^2)}{(x^2 + y^2)^3} = \frac{-1}{\rho} \frac{\partial p}{\partial y}$$

$$\frac{2B^2y}{(x^2 + y^2)^5} \left[ (x^2 - y^2)(y^2 - 3x^2) + 2x^2(x^2 - 3y^2) \right] = \frac{-1}{\rho} \frac{\partial p}{\partial y}$$

$$\frac{2B^2y}{(x^2 + y^2)^5}(-x^4 - 2x^2y^2 - y^4) = \frac{-1}{\rho} \frac{\partial p}{\partial y}$$

$$\frac{\partial p}{\partial y} = \frac{2B^2y\rho}{(x^2 + y^2)^3}$$

From (3),

$$0 = \frac{\partial p}{\partial z}$$

So, the pressure is only dependent on  $x$  &  $y$ .

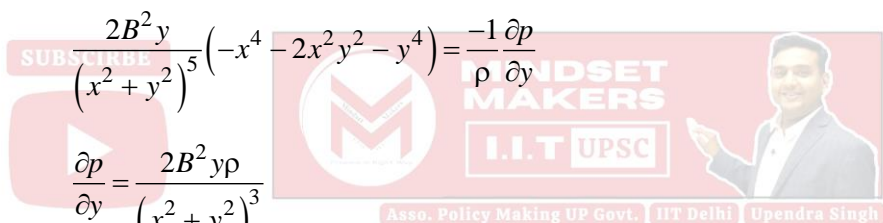
$$\therefore dp = \frac{\partial p}{\partial x} dx + \frac{\partial p}{\partial y} dy$$

$$dp = \frac{2B^2x\rho}{(x^2 + y^2)^3} dx + \frac{2B^2y\rho}{(x^2 + y^2)^3} dy$$

$$dp = \frac{B^2\rho}{(x^2 + y^2)^3} (2dx + 2dy)$$

$$dp = \frac{B^2\rho}{(x^2 + y^2)^3} d(x^2 + y^2)$$

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On integrating we get

$$P = \frac{-B^2 \rho}{2(x^2 + y^2)^2} + c, \text{ when } c \text{ is integrate constant,}$$

8 (a)

Given PDE is

$$\frac{\partial}{\partial y} \left( \frac{\partial \phi}{\partial x} + \phi \right) + 2x^2 y \left( \frac{\partial \phi}{\partial x} + \phi \right) = 0$$

$$\Rightarrow \frac{\partial^2 \phi}{\partial y \partial x} + \frac{\partial \phi}{\partial y} + 2x^2 y \frac{\partial \phi}{\partial x} + 2x^2 y \phi = 0 \quad \dots(1)$$

☐ - quadratic equation of (1) is  $R\lambda^2 + S\lambda + T = 0$ ,

Where  $R = 0, S = 1, T = 0$

∴ We have  $0\lambda^2 + 1\lambda + 0 = 0 \Rightarrow \lambda = 0$

∴ Characteristic curve:  $\frac{dy}{dx} + 0 = 0 \Rightarrow y = C_1$

∴  $u(x, y) = y$

Choosing  $v(x, y) = x$

Verifying Jacobians of  $u$  &  $v$ .

$$J(u, v) = \frac{\partial(u, v)}{\partial(x, y)} = \begin{vmatrix} \frac{\partial u}{\partial x} & \frac{\partial u}{\partial y} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{vmatrix} = \begin{vmatrix} 0 & 1 \\ 1 & 0 \end{vmatrix} \neq 0$$

∴  $u$  &  $v$  are independent.

Step (II): Now finding  $p, q, r, s, t$  by using (2) and (3).

$$p = \frac{\partial \phi}{\partial x} = \frac{\partial \phi}{\partial u} \frac{\partial u}{\partial x} + \frac{\partial \phi}{\partial v} \frac{\partial v}{\partial x} = \frac{\partial \phi}{\partial v} \Rightarrow \frac{\partial}{\partial x} = \frac{\partial}{\partial v}$$



$$p = \frac{\partial \phi}{\partial y} = \frac{\partial \phi}{\partial u} \frac{\partial u}{\partial y} + \frac{\partial \phi}{\partial v} \frac{\partial v}{\partial y} = \frac{\partial \phi}{\partial u} \cdot 1 + \frac{\partial \phi}{\partial v} \cdot 0 = \frac{\partial \phi}{\partial u} \Rightarrow \frac{\partial}{\partial y} = \frac{\partial}{\partial u}$$

$$s = \frac{\partial^2 \phi}{\partial y \partial x} = \frac{\partial^2 \phi}{\partial u \partial v}$$

Now using  $p, q, s$  in (1), we get required canonical form of (1) as

$$\frac{\partial^2 \phi}{\partial u \partial v} + \frac{\partial \phi}{\partial u} + 2v^2 u \frac{\partial \phi}{\partial v} + 2v^2 u = 0 \quad \dots(4)$$

Step (iii)

To solve (4):

$$\Rightarrow \frac{\partial^2 \phi}{\partial u \partial v} + \frac{\partial \phi}{\partial v} + 2v^2 u \left( \frac{\partial \phi}{\partial v} + \phi \right) = 0 \quad \dots(4)$$

Now, Let's take  $\frac{\partial^2 \phi}{\partial v} + \phi = z$



$\Rightarrow \frac{\partial^2 \phi}{\partial u \partial v} + \frac{\partial \phi}{\partial u} = \frac{\partial z}{\partial u} \quad \dots(5)$

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On using (5) in (4), we get

$$\frac{\partial z}{\partial u} + 2v^2 u z = 0$$

$$\Rightarrow \frac{1}{z} \frac{\partial z}{\partial u} = -2v^2 u$$

On integrating w.r.t  $u$ , we get

$$\log z + v^2 u^2 = \alpha(v); \alpha(v) \text{ is integration constant}$$

$$\Rightarrow z = e^{\alpha(v) - v^2 u^2}$$

$$\Rightarrow \frac{\partial \phi}{\partial v} + \phi = e^{\alpha(v) - v^2 u^2}$$

$$\Rightarrow \frac{\partial}{\partial v} (\phi e^v) = e^{\alpha(v) - v^2 u^2}$$

on integrating w.r.t v

$$\phi e^v = \int e^{\alpha(v)-v^2 u^2} dv + \beta(u); \beta(u) \text{ is integrating}$$

8. (b) Constructing the different table for the given problem.

x	y = f(x)	$\Delta$	$\Delta^2$	$\Delta^3$	$\Delta^4$
1	0	1			
2	1	7	6	6	0
3	8	19	12	6	0
4	27	37	18	6	0
5	64	61	24		
6	125				

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Let  $x = x_0 + uh$

$$\Rightarrow u = \frac{x - x_0}{h}$$

$$\Rightarrow u = \frac{x-1}{1} = (x-1)$$

By, Newtons formed interpolation formula, we have

$$f(x) = f(x_0) + u\Delta f(x_0) + \frac{u(u-1)}{2!} \Delta^2 f(x_0) + \frac{u(u-1)(u-2)}{3!} \Delta^3 f(x_0)$$

$$f(x) = 0 + (x-1)1 + \frac{(x-1)(x-2)}{2} \times 6 + \frac{(x-1)(x-2)(x-3)}{3!} \times 6$$

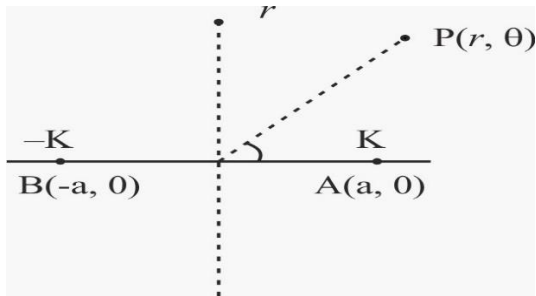
$$f(2.5) = 1.5 + \frac{1.5 \times (0.5)}{2} \times 6 + \frac{1.5 \times 0.5 \times (-0.5)}{6} \times 6$$

$$f(2.5) = 1.5 + 2.25 - 0.375$$

$$f(2.5) = 3.375$$

8. (c)





Due to vortices at A and B; the complex potential at P(r, θ) is

$$W = \frac{ikz}{4\pi a} + \frac{ikz}{2\pi} \log(z - a) - \frac{ik}{2\pi} \log(z + a) \quad \dots(1)$$

$$\phi + i\psi = \frac{ikz}{4\pi a} + \frac{ik}{2\pi} \log(z - a) - \frac{ik}{2\pi} \log(z + a)$$

∴ Streamlines are given by  $\psi = \text{constant}$ .

$$\Rightarrow \frac{ky}{4\pi a} + \frac{k}{2\pi} [\log|z - a| - \log|z + a|] = \text{constant}$$

$$\Rightarrow \frac{y}{a} + [\log|x + iy - a| - \log|x + iy + a|] = \text{constant}$$

$$\Rightarrow \log \frac{x^2 + (y - a)^2}{x^2 + (y + a)^2} + \frac{y}{a} = \text{constant}$$



As it's a long answer, so we must justify the formula:

- Let P(r, θ) be an arbitrary point.

$$\rightarrow \frac{\partial \psi}{\partial r} = -\frac{1}{r} \frac{\partial \phi}{\partial r}$$

$$\text{Also, } \because \text{ Outside the vortex } \nabla^2 \psi = \frac{\partial^2 \psi}{\partial x^2} + \frac{\partial^2 \psi}{\partial y^2} = 0$$

$$\because \nabla^2 \psi = \frac{\partial^2 \psi}{\partial r^2} + \frac{1}{r} \frac{\partial \psi}{\partial r} + \frac{1}{r^2} \frac{\partial^2 \psi}{\partial \theta^2} = 0$$

Note:- There is symmetry about origin,  $\psi$  must be independent of  $\theta$

We have

$$\frac{\partial^2 \psi}{\partial r^2} + \frac{1}{r} \frac{\partial \psi}{\partial r} + 0 = 0 \Rightarrow \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial \psi}{\partial r} \right) = 0$$

On integrating ;  $r \frac{\partial \psi}{\partial r} = c$ ;  $c$  is integration constant ...(6)

$$\psi = c \log r \dots(7)$$

$$\frac{\partial \psi}{\partial r} = \frac{c}{r} \Rightarrow \frac{-1}{r} \frac{\partial \phi}{\partial \theta} = \frac{c}{r}$$

On integrating;  $\phi = -c\theta$  ...(8)

Now, summarizing above discussion; we have

$$\text{The complex potential } w = \phi + i \psi = -c\theta + ic \log r \dots(9)$$

Let  $K$  be the 'circulation' in the circuit embracing the vortex (strength of vortex)

Remember

$$K = \int_{\theta=0}^{2\pi} \left( \frac{-1}{r} \frac{\partial \phi}{\partial \theta} \right) r d\theta = c \int_{\theta=0}^{2\pi} d\theta = 2\pi c \Rightarrow c = \frac{K}{2\pi} \dots(10)$$

Using (1) in (9), we have

$$\therefore \phi = -\frac{K}{2\pi} \theta, \psi = \frac{K}{2\pi} \log r$$

$$W = i \frac{K}{2\pi} \log z \quad \text{As; } z = re^{i\theta}; \log z = \log(re^{i\theta}) = \log r + i\theta \therefore i \log z = i(\log r + i\theta)$$

**Note:-**

i. If vortex is not at origin but at some point  $z = z_0$ ; then  $w = \frac{iK}{2\pi} \log(z - z_0)$

ii. If there are several rectilinear vortices, then

$$w = \frac{iK_1}{2\pi} \log(z - z_1) + \frac{iK_2}{2\pi} \log(z - z_2) + \dots + \frac{iK_n}{2\pi} \log(z - z_n)$$

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